PTO/SB/82 (06-03)
Patent and Trademark Office; U.S. DEPARTMENT OF COMMERCE

REVOCATION OF POWER OF ATTORNEY and APPOINTMENT OF NEW POWER OF ATTORNEY

Application Number	09/996,419
Filing Date	11/28/2001
First Named Inventor	Yulun Wang
Art Unit	3731
Examiner Name	G. Davis
Attorney Docket Number	022001-000233US

I hereby revoke all previous powers of attorney given in the above-identified application:

☐ A Power of Attorney is submitted herewith.

OR

☒ I hereby appoint the practitioners at Customer Number: **20350**

☒ Please change the correspondence address for the above-identified application to:

☒ The address associated with Customer Number: **20350**

OR

☐ Firm *or* Individual Name					
Address					
Address					
City					
Country		State		ZIP	
Telephone		Fax			

I am the:

☐ Applicant/Inventor.

☒ Assignee of record of the entire interest. See 37 CFR 3.71.
Statement under 37 CFR 3.73(b) is enclosed. (Form PTO/SB/96)

SIGNATURE of Applicant or Assignee of Record

Name	Susan Barnes, Chief Executive Officer		
Signature			
Date	11-24-03	Telephone	408-523-2160

NOTE: Signatures of all the inventors or assignees of record of the entire interest or their representative(s) are required. Submit multiple forms if more than one signature is required, see below*.

☐ *Total of _____ forms are submitted.

PTO/SB/96 (08-03)

Attorney Docket No. 022001-000233US

STATEMENT UNDER 37 CFR 3.73(b)

Applicant/Patent Owner: Yulun Wang et al.

Application No./Patent No.: 09/996,419 Filed/Issue Date: 11/28/2001

Entitled: AUTOMATED ENDOSCOPE SYSTEM FOR OPTIMAL POSITIONING

Computer Motion, Inc., a Delaware corporation

(Name of Assignee) (Type of Assignee, e.g., corporation, partnership, university, government agency, etc.)

states that it is:

1. ☒ the assignee of the entire right, title, and interest; or
2. ☐ an assignee of less than the entire right, title and interest.
The extent (by, percentage) of its ownership interest is _____%

in the patent application/patent identified above by virtue of either:

A. ☒ An assignment from the inventor(s) of the patent application/patent identified above. The assignment was recorded in the United States Patent and Trademark Office at Reel 08441, Frame 0131, or for which a copy thereof is attached.

OR

B. ☐ A chain of title from the inventor(s), of the patent application/patent identified above, to the current assignee as shown below:

1. From: _____ To: _____
The document was recorded in the United States Patent and Trademark Office at
Reel _____, Frame _____, or for which a copy thereof is attached.

2. From: _____ To: _____
The document was recorded in the United States Patent and Trademark Office at
Reel _____, Frame _____, or for which a copy thereof is attached.

3. From: _____ To: _____
The document was recorded in the United States Patent and Trademark Office at
Reel _____, Frame _____, or for which a copy thereof is attached.

☐ Additional documents in the chain of title are listed on a supplemental sheet.

☐ Copies of assignments or other documents in the chain of title are attached.

[NOTE: A separate copy (*i.e.*, the original assignment document or a true copy of the original document) must be submitted to Assignment Division in accordance with 37 CFR Part 3, if the assignment is to be recorded in the records of the USPTO. See MPEP 302.8]

The undersigned (whose title is supplied below) is authorized to act on behalf of the assignee.

2/23/04
Date

Susan Barnes
Typed or printed name

408-523-2100
Telephone number

Signature

Chief Executive Officer
Title

Atty Docket No.022001-000000

PTO FAX NO.: **703/ 306-5995**

ATTENTION: ASSIGNMENT BRANCH

OFFICIAL COMMUNICATION
FOR THE PERSONAL ATTENTION OF

ASSIGNMENT DIVISION

CERTIFICATION OF FACSIMILE TRANSMISSION

I hereby certify that the following document(s) re multiple applications listed on

SCHEDULE A

is being facsimile transmitted to the Patent and Trademark Office on the date shown below.

Number of pages being transmitted, including this page: **6**

Dated: 28 April 2004 Nancy Pizzo

NANCY PIZZO

Document(s) Attached

1. RECORDATION FORM COVER SHEET (1 pg)
2. RELEASE OF SECURITY INTEREST AND QUIT CLAIM ASSIGNMENT OF INTELLECTUAL PROPERTY (4 pgs)
3. SCHEDULE A (3 pgs)

PLEASE CONFIRM RECEIPT OF THIS PAPER BY RETURN FACSIMILE AT (415) 576-0300

TOWNSEND and TOWNSEND and CREW LLP
Two Embarcadero Center, 8th Floor
San Francisco, CA 94111-3834
Tel: 650-326-2400
Fax: 650-326-2422
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Attorney Docket No. 022001-000000US

Form **PTO-1595**
(Rev. 10-02)
OMB No. 0651-0027 (exp. 5/31/2004)

Recordation Form Cover Sheet
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U.S. Patent and Trademark Office

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To the Honorable Commissioner of Patents and Trademarks. Please record the attached original documents or copy thereof

1. Name of conveying party(ies):

AGILITY CAPITAL LLC

Additional name(s) of conveying party(ies) attached? ☒ Yes ☐ No.

3. Nature of conveyance:

☐ Assignment ☐ Merger
☒ Security Agreement ☐ Change of Name
☐ Other:

Execution Date: 4/28/2004

2. Name and address of receiving party(ies)

Name: Computer Motion, Inc.
Internal Address:
Street Address: 570 Kifer Road
City: Sunnyvale State: CA ZIP: 94086

Additional name(s) and address(es) attached? ☐ Yes ☒ No

4. Application number(s) or patent number(s):

If this document is being filed together with a new application, the execution date of the application is:

A. Patent Application No(s): **SEE SCHEDULE A**

B. Patent No(s): **SEE SCHEDULE A**

Additional numbers attached? ☐ Yes ☒ No

5. Name and address of party to whom correspondence concerning document should be mailed:

Name: Robert F. Kramer
TOWNSEND AND TOWNSEND AND CREW LLP
Two Embarcadero Center, Eighth Floor
San Francisco, California 94111-3834
(415) 576-0200

6. Total number of applications and patents involved 73

7. Total fee (37 CFR 3.41): ----------$2920.00

☐ Enclosed
☒ Authorized to be charged to deposit account

8. Deposit account number: **20-1430**

(Attach duplicate copy of this page if paying by deposit account)

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9. Statement and signature.

To the best of my knowledge and belief, the foregoing information is true and correct and any attached copy is a true copy of the original document.

Robert F. Kramer
Name of Person Signing
Atty. Reg. No. 51,242

Signature

04/28/2004
Date

Total number of pages including cover sheet, attachments and documents: 5

Mail documents to be recorded with required cover sheet information to:
Mail Stop Assignment Recordation Services
Director of the U.S. Patent and Trademark Office
P.O. Box 1450
Alexandria, VA 22313-1450

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60204681 v1

RELEASE OF SECURITY INTEREST AND QUIT-CLAIM ASSIGNMENT OF INTELLECTUAL PROPERTY

WHEREAS, **AGILITY CAPITAL LLC**, of 229 East Canon Perdido, Suite F, Santa Barbara, California 93101, hereinafter referred to as "Assignor," may have or once had a security interest and/or a claim of title to intellectual property rights in technology developed by Computer Motion, Inc., including some or all patents and patent applications listed in attached Schedule A;

WHEREAS, **COMPUTER MOTION, INC.**, a corporation of the State of California, located at 570 Kifer Road, Sunnyvale, California 94086, hereinafter referred to as "Assignee," is desirous of clarifying and/or obtaining clear title to these Intellectual Property rights, and to rights, if any, of Assignor to patents and patent applications listed in Schedule A;

Now, therefore, Assignor and Assignee agree as follows:

Assignor has assigned, and by these presents does assign to Assignee all right, title, and interest in and to all intellectual property rights of Assignor, if any, pertaining to any intellectual property developed by the Assignee, including rights to patents and patent applications listed in Schedule A, and including rights to any inventions, patent applications, letters patent and/or registrations which have or may hereafter be granted thereon, trade secrets, know-how, copyright, designs, and the like, in the United States and Foreign Countries, and also including any and all rights Assignor might otherwise retain in the patent applications listed in the appended Schedule A.

Assignor and Assignee agree that any dispute or controversy arising out of or relating to any interpretation, construction, performance or breach of this agreement shall be settled by arbitration to be held in Santa Clara County, California, in accordance with the rules then in effect of the American Arbitration Association. The arbitrator may grant injunctions or other relief in such dispute or controversy. The decision of the arbitrator shall be final, conclusive and binding on the parties to the arbitration. Judgment may be entered on the arbitrator's decision in any court having jurisdiction. Assignor and Assignee shall each pay one-half of the costs and expenses of such arbitration, and each shall separately pay counsel fees and expenses.

IN TESTIMONY WHEREOF, Assignor and Assignee have signed their names on the dates indicated.

Assignor:
Agility Capital LLC

Dated: 4/28/04

By: Robert A. Stein
Its: Chief Executive Officer

Attachments: *Appendix A*

60202798 v1

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Schedule A

(as attached to PTO/SB/82)

	Application No. Filing Date	Patent No. Issue Date	Title	Attorney Docket No.
1.	07/174653 03/29/1988	5019968 05/28/1991	Three Dimensional Vector Processor	022001-000100US
2.	07/553884 07/16/1990	5187796 02/16/1993	Three Dimensional Vector Co-Processor Having I, J, and K Register Files and I, J, K Execution Units	022001-000110US
3.	08/305415 09/13/1994	5515478 05/07/1996	Automated Endoscope System for Optimal Positioning	022001-000200US
4.	08/768103 12/16/1999	5754741 05/19/1998	Automated Endoscope System for Optimal Positioning	022001-000210US
5.	08/072982 06/03/1993	5524180 06/04/1996	Automated Endoscope System for Optimal Positioning	022001-000220US
6.	08/613866 03/11/1996	5907664 05/25/1999	Automated Endoscope System for Optimal Positioning	022001-000221US
7.	08/903955 07/31/1997	5841950 11/24/1998	Automated Endoscope System for Optimal Positioning	022001-000222US
8.	08/903914 07/31/1997	5815640 09/29/1998	Automated Endoscope System for Optimal Positioning	022001-000223US
9.	08/481926 06/06/1995	5657429 08/12/1997	Automated Endoscope System for Optimal Positioning	022001-000230US
10.	08/732015 10/16/1996	5878193 03/02/1999	Automated Endoscope System for Optimal Positioning	022001-000231US
11.	09/996419 11/28/2001		Automated Endoscope System for Optimal Positioning	022001-000233US
12.	08/346537 11/29/1994	5553198 09/03/1996	Automated Endoscope System for Optimal Positioning	022001-000241US
13.	08/529095 09/15/1995	5825982 10/20/1998	Head Cursor Control Interface for an Automated Endoscope System for Optimal Positioning	022001-000330US
14.	08/904047 07/31/1997	5911036 06/08/1999	Head Cursor Control Interface for an Automated Endoscope System for Optimal Positioning	022001-000331US
15.	09/179039 10/26/1998	6714841 03/30/2004	Head Cursor Control Interface for an Automated Endoscope System for Optimal Positioning	022001-000332US
16.	08/310665 09/22/1994	6463361 10/08/2002	Speech Interface for an Automated Endoscopic System	022001-000400US
17.	10/095488 03/11/2002		Speech Interface for an Automated Endoscopic System	022001-000401US
18.	08/322788 10/12/1994	5645520 07/08/1997	Shape Memory Alloy Actuated Rod for Endoscopic Instruments	022001-000500US
19.	08/603543 02/20/1996	5762458 06/09/1998	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000800US
20.	09/000703 12/30/1997	6244809 06/12/2001	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000802US
21.	09/000933 12/30/1997	6001108 12/14/1999	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000803US
22.	09/014698 01/28/1998	5971976 10/26/1999	Motion Minimalization and Compensation System for Use in Surgical Procedures	022001-000805US
23.	10/067730 02/04/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000811US
24.	09/953418 09/14/2001		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000820US

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Schedule A

(as attached to PTO/SB/82)

25.	08/755063 11/22/1996	5855583 01/05/1999	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000830US
26.	09/168527 10/08/1998	6007550 12/28/1999	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000831US
27.	10/289740 11/06/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000833US
28.	08/873190 08/15/2000	6102850 08/15/2000	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000840US
29.	09/557950 04/24/2000	6699177 03/02/2004	Method and Apparatus for Performing Minimally Invasive Surgical Procedures	022001-000841US
30.	10/339077 01/07/2003		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000842US
31.	10/737195 12/15/2003		Medical Robotic Arm that is Attached to an Operating Table	022001-000843US
32.	10/313810 12/06/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000845US
33.	09/156994 09/18/1998	6063095 05/16/2000	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000853US
34.	09/262134 03/03/1999	6436107 08/20/2002	Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000854US
35.	09/000934 12/30/1997		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000860US
36.	10/241139 09/10/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000861US
37.	10/241143 09/10/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000862US
38.	10/242168 09/11/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000863US
39.	10/310579 12/04/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000864US
40.	10/310405 12/04/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000865US
41.	10/310536 12/04/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000866US
42.	10/317890 12/11/2002		Method and Apparatus for Performing Minimally Invasive Cardiac Procedures	022001-000867US
43.	08/669629 06/24/1996		Multi-Functional Surgical Control System and Switching Interface	022001-000899US
44.	08/929024 09/15/1997		Multi-Functional Surgical Control System and Switching Interface	022001-000901US
45.	10/722837 11/26/2003		Multi-Functional Surgical Control System and Switching Interface	022001-000902US
46.	08/693352 08/06/1996	6646541 11/11/2003	General Purpose Distributed Operating Room Control System	022001-000910US
47.	08/958916 10/28/1997	6642836 11/04/2003	General Purpose Distributed Operating Room Control System	022001-000911US
48.	09/354944 07/15/1999	6496099 12/17/2002	General Purpose Distributed Operating Room Control System	022001-000920US
49.	10/315893 12/09/2002		General Purpose Distributed Operating Room Control System	022001-000921US

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Schedule A

(as attached to PTO/SB/82)

50.	09/615641 07/13/2000		Method and Apparatus for Accessing Medical Data Over a Network	022001-000930US
51.	10/666922 09/18/2003		General Purpose Distributed Operating Room Control System	022001-000940US
52.	09/287860 04/07/1999	6132441 10/17/2000	Rigidly-Linked Articulating Wrist With Decoupled Motion Transmission	022001-001000US
53.	10/013170 12/07/2001		Rigidly-Linked Articulating Wrist With Decoupled Motion Transmission	022001-001001US
54.	09/411442 10/01/1999		Heart Stabilizer	022001-001300US
55.	09/870331 05/29/2001		Heart Stabilizer	022001-001310US
56.	09/675824 09/29/2000		Heart Stabilizer Support Arm	022001-001500US
57.	09/639489 08/15/2000	6726699 04/27/2004	Universal Instrument Guide or Cannula for Endoscopic Surgery	022001-001600US
58.	09/458175 12/09/1999	6591239 07/08/2003	Voice Controlled Surgical Suite	022001-001700US
59.	09/847736 05/01/2001		Pivot Point Arm for a Robotic System Used to Perform a Surgical Procedure	022001-001900US
60.	10/411651 04/10/2003		Pivot Point Arm for a Robotic System Used to Perform a Surgical Procedure	022001-001910US
61.	09/935555 08/21/2001		Robotically Controlled Surgical Instrument, Visual Force-Feedback	022001-002000US
62.	09/949050 09/07/2001	6728599 04/27/2004	Modularity System for Computer Assisted Surgery	022001-002100US
63.	10/423432 04/24/2003		Modularity System for Computer Assisted Surgery	022001-002110US
64.	10/418403 04/17/2003		Modularity System for Computer Assisted Surgery	022001-002120US
65.	10/423429 04/24/2003		Modularity System for Computer Assisted Surgery	022001-002121US
66.	10/423431 04/24/2003		Modularity System for Computer Assisted Surgery	022001-002122US
67.	10/423428 04/24/2003		Modularity System for Computer Assisted Surgery	022001-002123US
68.	10/012602 12/08/2001		Multifunctional Handle for a Medical Robotic	022001-002200US
69.	10/013067 12/07/2001		Microwrist System for Surgical Procedures	022001-002300US
70.	10/006905 11/07/2001	6730021 05/04/2004	Tissue Spreader with Force Measurement, Force Indication or Force Limitation	022001-002600US
71.	10/051796 01/16/2002		Minimally Invasive Surgical Training Using Robotics and Tele-Collaboration	022001-002700US
72.	10/246236 09/17/2002		Tele-Medicine System that Transmits an Entire State of a Subsystem	022001-002710US
73.	10/460382 06/11/2003		Surgical Instrument With a Universal Wrist	022001-002800US

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